



Distributed Consensus in Multi-vehicle Cooperative Control: Theory and Applications (Communications and Control Engineering)

Wei Ren, Randal Beard

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
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Assuming only neighbor-neighbor interaction among vehicles, this monograph develops distributed consensus strategies that ensure that the information states of all vehicles in a network converge to a common value. Readers learn to deal with groups of autonomous vehicles in aerial, terrestrial, and submarine environments. Plus, they get the tools needed to overcome impaired communication by using constantly updated neighbor-neighbor interchange.

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